

15_VECM

QuantFit Estimator Standard Operating Procedure

SOP: Vector Error Correction Model (VECM)

VAR for cointegrated I(1) systems

=> Use VECM when $k \geq 2$ I(1) variables are cointegrated - the levels VAR is non-stationary, the VECM is.

1. Purpose

VECM expresses a cointegrated VAR in error-correction form. The Johansen procedure identifies the cointegrating rank $r \in [1, k-1]$ and estimates the cointegrating vectors β and adjustment matrix α . Short-run dynamics are captured by lagged Δ -terms.

2. When to use this estimator

All variables I(1) with at least one cointegrating relationship (Johansen rank ≥ 1).

Multivariate framework where VAR in levels would be misspecified.

3. Required data structure

All k series I(1) per Stage 3.

Johansen test confirms $r \geq 1$ cointegrating vectors.

$T \geq 2 \times k \times p$ typical.

4. Mathematical formulation

$\Delta Y_t = \alpha \beta' Y_{t-1} + \sum \Gamma_i \Delta Y_{t-i} + \epsilon_t$

β : $k \times r$ matrix of cointegrating vectors (long-run equilibria).

α : $k \times r$ adjustment matrix; $(\alpha \beta')$ is rank- r .

Γ_i : short-run $k \times k$ coefficient matrices on lagged differences.

Reduced-rank regression solves α and β simultaneously (Johansen).

5. Pre-estimation diagnostics

All variables I(1).

Johansen trace and max-eigenvalue tests for rank r .

Lag selection in the underlying VAR (AIC / BIC / HQ).

6. Estimation procedure

Determine VAR lag order p in levels.

Run Johansen reduced-rank regression to get r .

Estimate $\Delta Y_t = \alpha \beta' Y_{t-1} + \sum \Gamma_i \Delta Y_{t-i} + \epsilon_t$

with rank r .

Reconstruct levels VAR for Cholesky IRF / FEVD.

Run residual diagnostics (autocorrelation, normality, stability).

7. Output produced

8. Output interpretation

$\beta'Y_{t-1}$ are the long-run equilibrium errors; α is the adjustment toward them.

Sign and magnitude of α reveals which variables bear the burden of correction.

IRF / FEVD interpreted same as VAR after the levels reconstruction.

9. Post-estimation diagnostics

Stability (spectral radius < 1 after rank reconstruction).

Residual autocorrelation, normality, ARCH-LM.

Robustness across rank choice.

10. Common pitfalls

Mis-specifying the rank produces inconsistent α and β .

Mixing $I(0)$ and $I(1)$ variables - drop $I(0)$ ones or transform first.

Cholesky ordering still matters for IRF interpretation post-reconstruction.

11. Reporting checklist

Johansen trace / max-eig test results and chosen rank.

Cointegrating vectors β (normalised).

Adjustment matrix α with significance.

IRF / FEVD panels.

Stability and residual diagnostics.

12. References

Johansen, S. (1995). Likelihood-Based Inference in Cointegrated Vector Autoregressive Models. Oxford.

Lütkepohl, H. (2005). New Introduction to Multiple Time Series Analysis. Springer.

Field | Meaning

metadata['cointegratingRank'] | Johansen-selected r

metadata['cointegratingVectors'] | β as flattened text block

metadata['adjustmentMatrix'] | α

varIRF / varFEVD | Computed from the implied levels VAR

companionSpectralRadius | Stability
residuals | VECM residuals